

AMS526: Numerical Analysis I (Numerical Linear Algebra)

Lecture 5: Singular Value Decomposition

Xiangmin Jiao

SUNY Stony Brook

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Review

- Matrix norms

- ▶ 1-norm
- ▶ ∞ -norm
- ▶ 2-norm
- ▶ Frobenius norm

Invariance under Unitary Multiplication

Theorem

For any $\mathbf{A} \in \mathbb{C}^{m \times n}$ and unitary $\mathbf{Q} \in \mathbb{C}^{m \times m}$, we have

$$\|\mathbf{QA}\|_2 = \|\mathbf{A}\|_2 \text{ and } \|\mathbf{QA}\|_F = \|\mathbf{A}\|_F.$$

In other words, 2-norm and Frobenius norms are invariant under unitary multiplication.

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Proof for 2-norm: $\|\mathbf{Qy}\|_2 = \|\mathbf{y}\|_2$ for $\mathbf{y} \in \mathbb{C}^m$ and therefore $\|\mathbf{QA}\mathbf{x}\|_2 = \|\mathbf{A}\mathbf{x}\|_2$ for $\mathbf{x} \in \mathbb{C}^n$. It then follows from definition of 2-norm.

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Proof for Frobenius norm:

$$\|\mathbf{QA}\|_F = \text{tr}((\mathbf{QA})^* \mathbf{QA}) = \text{tr}(\mathbf{A}^* \mathbf{Q}^* \mathbf{QA}) = \text{tr}(\mathbf{A}^* \mathbf{A}) = \|\mathbf{A}\|_F.$$

Geometric Observation

- The image of unit sphere under any $m \times n$ matrix is a *hyperellipse*
- Give a unit sphere S in \mathbb{R}^n , let $\mathbf{A}S$ denote the shape after transformation
- SVD is

$$\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^*$$

where $\mathbf{U} \in \mathbb{C}^{m \times m}$ and $\mathbf{V} \in \mathbb{C}^{n \times n}$ is unitary and $\mathbf{\Sigma} \in \mathbb{R}^{m \times n}$ is diagonal

- *Singular values* are diagonal entries of $\mathbf{\Sigma}$, correspond to the principal semiaxes, with entries $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n \geq 0$.
- *Left singular vectors* of \mathbf{A} are column vectors of \mathbf{U} and are oriented in the directions of the principal semiaxes of $\mathbf{A}S$
- *Right singular vectors* of \mathbf{A} are column vectors of \mathbf{V} and are the preimages of the principal semiaxes of $\mathbf{A}S$
- $\mathbf{A}\mathbf{v}_j = \sigma_j\mathbf{u}_j$ for $1 \leq j \leq n$

Existence of SVD

Theorem

(Existence) Every matrix $\mathbf{A} \in \mathbb{C}^{m \times n}$ has an SVD.

Proof.

Let $\sigma_1 = \|\mathbf{A}\|_2$. There exists $\mathbf{v}_1 \in \mathbb{C}^n$ with $\|\mathbf{v}_1\|_2 = 1$ and $\|\mathbf{A}\mathbf{v}_1\|_2 = \sigma_1$. Let \mathbf{U}_1 and \mathbf{V}_1 be unitary matrices whose first columns are $\mathbf{A}\mathbf{v}_1/\sigma_1$ (or any unit-length vector if $\sigma_1 = 0$) and \mathbf{v}_1 , respectively. Note that

$$\mathbf{S} = \mathbf{U}_1^* \mathbf{A} \mathbf{V}_1 = \begin{bmatrix} \sigma_1 & \mathbf{0}^* \\ \mathbf{0} & \mathbf{B} \end{bmatrix}. \quad (1)$$

We then prove by induction using (1). If $m = 1$ or $n = 1$, then \mathbf{B} is empty and we have $\mathbf{A} = \mathbf{U}_1 \mathbf{S} \mathbf{V}_1^*$. Otherwise, suppose $\mathbf{B} = \mathbf{U}_2 \mathbf{\Sigma}_2 \mathbf{V}_2^*$, and

therefore $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^*$ where $\mathbf{U} = \mathbf{U}_1 \begin{bmatrix} 1 & \mathbf{0}^* \\ \mathbf{0} & \mathbf{U}_2 \end{bmatrix}$, $\mathbf{\Sigma} = \begin{bmatrix} \sigma_1 & \mathbf{0}^* \\ \mathbf{0} & \mathbf{\Sigma}_2 \end{bmatrix}$, and

$\mathbf{V} = \mathbf{V}_1 \begin{bmatrix} 1 & \mathbf{0}^* \\ \mathbf{0} & \mathbf{V}_2 \end{bmatrix}$. \mathbf{U} and \mathbf{V} are unitary. □

Uniqueness of SVD

Theorem

*(Uniqueness) The singular values $\{\sigma_j\}$ are uniquely determined. If \mathbf{A} is square and the σ_j are distinct, the left and right singular vectors are uniquely determined **up to complex signs**.*

Main idea of proof: Based on 2-norm and prove by induction. Consider the case where the σ_j are distinct. The 2-norm is unique, so is σ_1 . Once σ_1 , \mathbf{u}_1 , and \mathbf{v}_1 are determined, the remainder of SVD is determined by the space orthogonal to \mathbf{v}_1 . Because \mathbf{v}_1 is unique up to sign, the orthogonal subspace is uniquely defined. Then prove by induction.

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- Question: What if we flip the sign of a singular vector?
- Question: What if σ_i is not distinct?

Two Different Types of SVD

- **Full SVD:** $U \in \mathbb{C}^{m \times m}$, $\Sigma \in \mathbb{R}^{m \times n}$, and $V \in \mathbb{C}^{n \times n}$ is

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- Furthermore, notice that

$$A = \sum_{i=1}^{\min\{m,n\}} \sigma_i u_i v_i^*$$

so we can keep only entries of U and V corresponding to nonzero σ_i .