

AMS526: Numerical Analysis I (Numerical Linear Algebra)

Lecture 13: Conditioning of Least Squares Problems; Stability of Least Squares Algorithms

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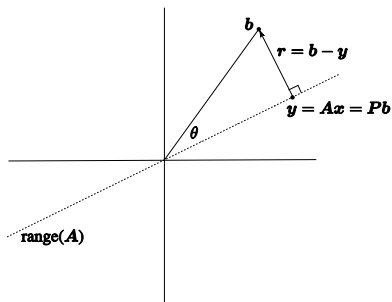
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Four Conditioning Problems

- Least squares problem: Given $\mathbf{A} \in \mathbb{C}^{m \times n}$ with full rank and $\mathbf{b} \in \mathbb{C}^m$,

$$\min_{\mathbf{x} \in \mathbb{C}^n} \|\mathbf{b} - \mathbf{A}\mathbf{x}\|$$

- Its solution is $\mathbf{x} = \mathbf{A}^+ \mathbf{b}$. Another quantity is $\mathbf{y} = \mathbf{A}\mathbf{x} = \mathbf{P}\mathbf{b}$, where $\mathbf{P} = \mathbf{A}\mathbf{A}^+$



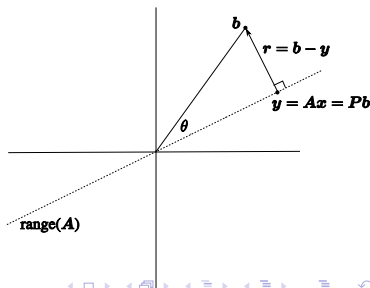
- Consider \mathbf{A} and \mathbf{b} as input data, and \mathbf{x} and \mathbf{y} as output. We then have four conditioning problems:

Input \ Output	\mathbf{y}	\mathbf{x}
\mathbf{b}	$\kappa_{\mathbf{b} \rightarrow \mathbf{y}}$	$\kappa_{\mathbf{b} \rightarrow \mathbf{x}}$
\mathbf{A}	$\kappa_{\mathbf{A} \rightarrow \mathbf{y}}$	$\kappa_{\mathbf{A} \rightarrow \mathbf{x}}$

Some Prerequisites

- These conditioning problems are important and subtle.
- We focus on the second column, namely $\kappa_{\mathbf{b} \rightarrow \mathbf{x}}$ and $\kappa_{\mathbf{A} \rightarrow \mathbf{x}}$
 - ▶ Understanding $\kappa_{\mathbf{b} \rightarrow \mathbf{y}}$ and $\kappa_{\mathbf{A} \rightarrow \mathbf{y}}$ is prerequisite
 - ▶ Note: Linear system $\mathbf{A}\mathbf{x} = \mathbf{b}$ for nonsingular $\mathbf{A} \in \mathbb{C}^{m \times m}$ is a special case of least squares problems, where $\mathbf{y} = \mathbf{b}$.
- We will focus on intuitive understanding instead of rigorous proof
- Three quantities (All norms are 2-norms)

- ▶ Condition number of \mathbf{A} :
$$\kappa(\mathbf{A}) = \|\mathbf{A}\| \|\mathbf{A}^+\| = \sigma_1 / \sigma_n$$
- ▶ Angle between \mathbf{b} and \mathbf{y} :
$$\theta = \arccos \frac{\|\mathbf{y}\|}{\|\mathbf{b}\|}$$
- ▶ Orientation of \mathbf{y} with $\text{range}(\mathbf{A})$:
$$\eta = \frac{\|\mathbf{A}\| \|\mathbf{x}\|}{\|\mathbf{y}\|}$$
 (how far \mathbf{y} is from \mathbf{u}_1 , left singular vector of \mathbf{A} corresponding to σ_1 ?)



Sensitivity of \mathbf{y} to Perturbations in \mathbf{b}

- Intuition: The larger θ is, the more sensitive \mathbf{y} is in terms of relative error
- Analysis: $\mathbf{y} = \mathbf{P}\mathbf{b}$, so

$$\kappa_{\mathbf{b} \rightarrow \mathbf{y}} = \frac{\|\mathbf{P}\|}{\|\mathbf{y}\|/\|\mathbf{b}\|} = \frac{\|\mathbf{b}\|}{\|\mathbf{y}\|} = \frac{1}{\cos \theta},$$

where $\|\mathbf{P}\| = 1$

Input \ Output	\mathbf{y}	\mathbf{x}
\mathbf{b}	$\frac{1}{\cos \theta}$	
\mathbf{A}		

- Question: When the maximum is attained for perturbation $\delta \mathbf{b}$?

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Input \ Output	\mathbf{y}	\mathbf{x}
\mathbf{b}	$\frac{1}{\cos \theta}$	
\mathbf{A}		

- Question: When the maximum is attained for perturbation $\delta\mathbf{b}$?
- Answer: When $\delta\mathbf{b}$ is in range(\mathbf{A})

Sensitivity of \mathbf{x} to Perturbations in \mathbf{b}

- Intuition: It depends on how sensitive \mathbf{y} is to \mathbf{b} , and how \mathbf{y} lies within $\text{range}(\mathbf{A})$
- Analysis: $\mathbf{x} = \mathbf{A}^+ \mathbf{b}$, so

$$\kappa_{\mathbf{b} \rightarrow \mathbf{x}} = \frac{\|\mathbf{A}^+\|}{\|\mathbf{x}\|/\|\mathbf{b}\|} = \|\mathbf{A}^+\| \frac{\|\mathbf{b}\|}{\|\mathbf{y}\|} \frac{\|\mathbf{y}\|}{\|\mathbf{x}\|} = \|\mathbf{A}^+\| \frac{1}{\cos \theta} \frac{\|\mathbf{A}\|}{\eta} = \frac{\kappa(\mathbf{A})}{\eta \cos \theta},$$

where $\eta = \|\mathbf{A}\| \|\mathbf{x}\| / \|\mathbf{y}\|$

Input \ Output	\mathbf{y}	\mathbf{x}
\mathbf{b}	$\frac{1}{\cos \theta}$	$\frac{\kappa(\mathbf{A})}{\eta \cos \theta}$
\mathbf{A}		

- Assume $\cos \theta = O(1)$, $\kappa_{\mathbf{b} \rightarrow \mathbf{x}}$ can lie anywhere between 1 and $O(\kappa(\mathbf{A}))!$
- Question: When the maximum is attained for perturbation $\delta \mathbf{b}$?

Sensitivity of \mathbf{x} to Perturbations in \mathbf{b}

- Intuition: It depends on how sensitive \mathbf{y} is to \mathbf{b} , and how \mathbf{y} lies within $\text{range}(\mathbf{A})$
- Analysis: $\mathbf{x} = \mathbf{A}^+ \mathbf{b}$, so

$$\kappa_{\mathbf{b} \rightarrow \mathbf{x}} = \frac{\|\mathbf{A}^+\|}{\|\mathbf{x}\|/\|\mathbf{b}\|} = \|\mathbf{A}^+\| \frac{\|\mathbf{b}\|}{\|\mathbf{y}\|} \frac{\|\mathbf{y}\|}{\|\mathbf{x}\|} = \|\mathbf{A}^+\| \frac{1}{\cos \theta} \frac{\|\mathbf{A}\|}{\eta} = \frac{\kappa(\mathbf{A})}{\eta \cos \theta},$$

where $\eta = \|\mathbf{A}\| \|\mathbf{x}\| / \|\mathbf{y}\|$

Input \ Output	\mathbf{y}	\mathbf{x}
\mathbf{b}	$\frac{1}{\cos \theta}$	$\frac{\kappa(\mathbf{A})}{\eta \cos \theta}$
\mathbf{A}		

- Assume $\cos \theta = O(1)$, $\kappa_{\mathbf{b} \rightarrow \mathbf{x}}$ can lie anywhere between 1 and $O(\kappa(\mathbf{A}))!$
- Question: When the maximum is attained for perturbation $\delta \mathbf{b}$?
- Answer: When $\delta \mathbf{b}$ is in subspace spanned by left singular vectors corresponding to smallest singular values
- Question: What if \mathbf{A} is a nonsingular matrix? $\kappa_{\mathbf{b} \rightarrow \mathbf{x}}$ can lie anywhere

Sensitivity of \mathbf{y} and \mathbf{x} to Perturbations in \mathbf{A}

- The relationships are nonlinear, because $\text{range}(\mathbf{A})$ changes due to $\delta\mathbf{A}$
- Intuitions:
 - ▶ The larger θ is, the more sensitive \mathbf{y} is in terms of relative error.
 - ▶ Tilting of $\text{range}(\mathbf{A})$ depends on $\kappa(\mathbf{A})$.
 - ▶ For \mathbf{x} , it depends where \mathbf{y} lies within $\text{range}(\mathbf{A})$

Input \ Output	\mathbf{y}	\mathbf{x}
\mathbf{b}	$\frac{1}{\cos \theta}$	$\frac{\kappa(\mathbf{A})}{\eta \cos \theta}$
\mathbf{A}	$\leq \frac{\kappa(\mathbf{A})}{\cos \theta}$	$\leq \kappa(\mathbf{A}) + \frac{\kappa(\mathbf{A})^2 \tan \theta}{\eta}$

- For second row, bounds are not necessarily tight
- Assume $\cos \theta = O(1)$, $\kappa_{\mathbf{A} \rightarrow \mathbf{x}}$ can lie anywhere between $\kappa(\mathbf{A})$ and $O(\kappa(\mathbf{A})^2)$

Algorithms for Solving Least Squares Problems

There are many variants of algorithms for solving least squares problems

- Extremely unstable
 - ▶ Normal equations: solve $\mathbf{A}^T \mathbf{A} \mathbf{x} = \mathbf{A}^T \mathbf{b}$
- Unstable
 - ▶ Classical Gram-Schmidt
 - ▶ Modified Gram-Schmidt with explicit \mathbf{Q}
- Stable
 - ▶ Modified Gram-Schmidt with augmented system of equations with implicit \mathbf{Q}
 - ▶ Householder QR (with/without pivoting, explicit or implicit \mathbf{Q})
 - ▶ Singular value decomposition
- Demo of different methods
- Note that in general, only SVD is robust for solving rank deficient least squares problems