

# AMS 526 Homework 2

Due: Wednesday 09/26 in class

1. (15 points) Consider the matrix

$$A = \begin{bmatrix} 2 & 11 \\ 10 & 5 \end{bmatrix}.$$

- (a) (3 points) By hand calculation, determine the singular values of  $A$ . (Hint: Compute the eigenvalue of  $A^T A$ .)
  - (b) (6 points) By hand calculation, compute the left singular vectors  $u_i$  and their corresponding right singular vectors  $v_i$  of  $A$ .
  - (c) (3 points) Write down the SVD of  $A^T$ .
  - (d) (3 points) Compute the condition number of  $A$  in 2-norm.
2. (15 points) Let  $P \in \mathbb{R}^{n \times n}$  be an orthogonal projector.

- (a) (5 points) Show that  $I - P$  is also an orthogonal projector. What space does  $I - P$  project onto?
- (b) (5 points) Show that  $I - 2P$  is orthogonal.
- (c) (5 points) Consider the matrix

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 0 \end{bmatrix}.$$

What is the orthogonal projector  $P$  onto  $\text{range}(A)$ ? What is its complementary orthogonal projector?

3. (15 points) Each of the following problems describes an algorithm implemented on a computer satisfying the two axioms of floating point numbers (axioms (13.5) and (13.7) in the textbook). For each problem, answer whether the algorithm is *backward stable*, *stable but not backward stable*, or *unstable*. Prove your assertion or give a reasonably convincing argument.

- (a) (5 points) Data:  $x, y \in \mathbb{R}^n$ . Solution:  $x^T y$ , computed as  $x_1 \otimes y_1 \oplus x_2 \otimes y_2 \oplus \cdots \oplus x_n \otimes y_n$ , where  $\oplus$  and  $\otimes$  denotes floating-point addition and multiplication, respectively.
  - (b) (5 points) Data: none. Solution:  $e$ , computed by summing  $\sum_{k=0}^{\infty} 1/k!$  from left to right using floating-point multiplication  $\otimes$  and floating-point addition  $\oplus$ , stopping when a summand is reached of magnitude  $< \epsilon_{\text{machine}}$ .
  - (c) (5 points) Data: none. Solution:  $e$ , computed by the same algorithm as above except that the series is summed from right to left.
4. (15 points) Suppose  $U = I - B$  is unit upper triangular, where  $B \in \mathbb{R}^{n \times n}$ .

- (a) (5 points) Show that

$$U^{-1} = I + B + B^2 + \cdots + B^{n-1}.$$

- (b) (5 points) What is the value of  $\|U^{-1}\|_F$  if  $b_{ij} = 1$  for  $i < j$ ?
- (c) (5 points) What is the condition number of  $U$  in 1-norm if  $b_{ij} = 1$  for  $i < j$ ?
5. (10 points) Gaussian elimination can be used to compute the inverse  $A^{-1}$  of a nonsingular matrix  $A \in \mathbb{R}^{n \times n}$ , though it is rarely really necessary to do so.
- (a) (5 points) Describe an algorithm for computing  $A^{-1}$  by solving  $n$  systems of equations, and show that its asymptotic operation count is  $\frac{8}{3}n^3$  flops.
- (b) (5 points) Describe a variant of your algorithm, taking advantage of sparsity, that reduces the operations count to  $2n^3$  flops.
6. (30 points) Write a routine in MATLAB to estimate the condition number of a real matrix  $A$  using 1-norm. You will need to compute  $\|A\|_1$ , which is easy, and estimate  $\|A^{-1}\|_1$ , which is more challenging. One way to estimate  $\|A^{-1}\|_1$  is to take it as the ratio  $\|z\|_1/\|y\|_1$ , where  $z$  is the solution to  $Az = y$  and  $y$  is picked by some heuristic to maximize the ratio.

We choose  $y$  as the solution to the system  $A^T y = c$ , where  $c$  is a vector each of whose components is  $\pm 1$ , with the sign for each component chosen by the following heuristic. Using the factorization  $PA = LU$  (you may use MATLAB's routine `lu`), the system  $A^T y = c$  is solved in two stages, successively solving the triangular systems  $U^T v = c$  and  $L^T P y = v$ . At each step of the first triangular solution, choose the corresponding component of  $c$  to be 1 or  $-1$ , depending on which will make the resulting component of  $v$  larger in magnitude. You will need to write a custom triangular solution routine to implement the selection of  $c$ . Then solve the second triangular system  $L^T P y = v$  in the usual way for  $y$ , for which you can use MATLAB's backslash “\” operator. The idea here is that any ill-conditioning in  $A$  will be reflected in  $U$ , resulting in a relatively large  $v$ . The relative well-conditioning unit triangular matrix  $L$  will then preserve this relationship, resulting in relatively large  $y$ .

Test your program on the Hilbert matrix of order  $n = 2, 3, \dots, 12$ , which has entries  $h_{ij} = 1/(i + j - 1)$ . For example, a  $3 \times 3$  Hilbert matrix has entries

$$\begin{bmatrix} 1 & 1/2 & 1/3 \\ 1/2 & 1/3 & 1/4 \\ 1/3 & 1/4 & 1/5 \end{bmatrix}.$$

To check the quality of your estimates, compute  $A^{-1}$  explicitly using the LU factorization that was already computed and then compute the condition number  $\|A\|_1 \|A^{-1}\|_1$ . Plot the estimated condition numbers and the explicitly computed condition numbers for the Hilbert matrix of order  $n = 2, 3, \dots, 12$  (using the horizontal axis for  $n$  and the vertical axis for the condition numbers). Compare the required flops of the two approaches (i.e., estimation and explicit computation), and also plot their running times for different  $n$ . To obtain reliable timing of a procedure, you may need to run it repeatedly for hundreds of iterations and then take the average (use the `tic()` and `toc()` functions outside the iterations).

Submit your programs, the plots, and a brief discussion of your results.